

LIST OF PATENTS AND PUBLICATIONS FOR APPLICANTS' INFORMATION DISCLOSURE STATEMENT

INFORMATION DISCLOSURE STATEMENT BY APPLICANT	Application Number	10/718,913
	Filing Date	November 21, 2003
	Inventor	McBean et al
	Art Unit	3772
	Examiner	Brown, Michael
	Atty Docket	1118/A04

Non-Patent References		
Examiner's Initials	Ref. No.	Document Number, Publication Date, Inventor
	BQ	Lum, et al., "A Robotic System for Upper-Limb Exercises to Promote Recovery of Motor Function Following Stroke", ICORR '99: International Conference on Rehabilitation Robotics, Stanford, CA, pages 235-239
	BR	Lum, et al., "Quantification of Force Abnormalities During Passive and Active-Assisted Upper-Limb Reaching Movements in Post-Stroke Hemiparesis", 1999, IEEE Trans on Biomed, Vol 46, No 6, pages 652-662
	BS	Lum, et al., "Robotic Assist Devices for Bimanual Physical Therapy Preliminary Experiments", 1993, IEEE Transactions on Rehabilitation Engineering, Vol. 1, No. 3, pages 185-191
	BT	Parsons, et al., "An Adaptable User Interface and Controller for a Rehabilitation Robotoc Arm, 1997, ICAR, pages 919-923
	BU	Popovic, et al., "Hybrid Assistance System-The Motor Neuroprosthesis", 1989, IEEE Transactions on Biomedical Engineering, Vol. 36, No. 7, pages 729-737
	BV	Rabischong, et al., "Control and Command of a Six Degrees of Freedom Active Electrical Orthosis for Paraplegic Patient", 1990, IEEE International Workshop on Intelligent Robots and Systems, pages 987-991
	BW	Reinkensmeyer, et al., "Guidance-Based Quantification of Arm Impairment Following Brain Injury: A Pilot Study", 1999, IEEE Transactions on Rehabilitation Engineering, Vol 7, No. 1, pages 1-11
	BX	Romilly, et al., "A Functional Task Analysis and Motion Stimulation for the Development of a Powered Upper-Limb Orthosis", 1994, IEEE Transactions on Rehabilitation Engineering, Vol. 2, No 3, pages 119-129

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	BY	Timoszyk, et al., "Robot-Assisted Locomotion Training after Spinal Cord Injury – Comparison of Rodent Stepping in Virtual and Physical Treadmill Environments", Department of Mechanical and Aerospace Engineering and Center for Biomedical Engineering, University of California, Irvine, 1990 IEEE International Conference, pages 1-14
	BZ	Triolo, et al., "The Theoretical Development of a Multichannel Time-Series Myoprocessor for Simultaneous Limb Function Detection and Muscle Force Estimation", 1989, IEEE Transactions on Biomedical Engineering, Vol. 36, No. 10, pages 1004-1017
	CA	Wu, et al., "A Study of Neuromuscular-like Control in Rehabilitation Robot", Proceedings of the 1996 IEEE International Conference on Robotics and Automation, Minneapolis, MN, 0-7803-2988-4/96, April 1996, pages 1178-1183
	CB	Zardoshti-Kermani, et al., "EMG Feature Evaluation for Movement Control of Upper Extremity Prostheses", 1995, IEEE Transactions on Rehabilitation Engineering, Vol. 3, No. 4, pages 324-333

Examiner Signature: _____

Date Considered: _____

EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609; draw a line through the citation *if not* in conformance and not considered. Include copy of this form with next communication to applicant.

Identification of Person Making This Information Disclosure Statement

The person making this statement is the practitioner who signs below on the basis of the information supplied by the inventor and in the practitioner's file.

Respectfully submitted,

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